### drylin<sup>®</sup> Low Cost Automation

### drylin<sup>®</sup> E | Stepper motors | Product overview Various NEMA stepper motor options



Motor with stranded wires

Motors with stranded wires are the least expensive and the most common stepper motors. The connecting wires (length 30cm) for this type exit from the housing and will be configured with a JST connector. They are usually installed in machines and equipment that have an additional housing or are used in clean environments.



Motor with connector

The connector interface provides a high IP65 protection level (IP: International Protection). The higher the IP rating, the better the motor is protected from the ingress of dirt and water.



#### Motor with connector and encoder

The encoder (for increased machine reliability) sends signals from the motor to the motor control. The encoder verifies that the required linear motion has occurred precisely.

All motors are delivered with a machined flat motor shaft (D-cut) for increased torque resistance.

### Installation sizes of NEMA stepper motors

### NEMA11: Tiny but with plenty of power

This motor has very compact dimensions. Even so, heavy loads can be moved with the suitable lead screw pitch. This motor is typically used on small test and analysis equipment and miniature adjustments.

### NEMA17: Small, but lots of power

This little motor has impressive torque and high RPMs. Reliable operation at fast travel with low loads.

### NEMA23: The best known stepper motor size

Versatile choice due to the high torque and rotational speed. This motor is the best choice for most applications with medium loads.



Motor with connector, encoder and brake

The brake can hold the payload in position when the motor is not under power. This is used as a safety feature during power failures – recommended for vertically mounted systems.

### NEMA23XL: The power motor in the medium installation size

A development extension of the typical NEMA23 with nearly twice the torque. The assembly dimensions are identical to the NEMA23, allowing many applications.

### NEMA34: The power pack in the large installation size

Applications with higher loads are implemented using the largest installation size. Heavy-duty format adjustments or parallel dual axis setups are among its primary duties.



### drylin® E | Stepper motors | Technical data

drylin<sup>®</sup> automation

### **Technical data**

Distance over hubs		28	42	56	60	86
Motor		NEMA11	NEMA17	NEMA23	NEMA23XL	NEMA34
Connection dimensions	[mm]	28 x 28	42 x 42	56 x 56	60 x 60	86 x 86
Maximum voltage	[VDC]	60	60	60	60	60
Nominal voltage	[VDC]	24-48	24-48	24-48	24-48	24-48
Nominal current	[A]	1.0	1.8	4.2	4.2	6.4
Holding torque	[Nm]	0.13	0.5	2.0	3.5	5.9
Ratchet torque	[Nm]	0.004	0.022	0.068	0.075	0.210
Step angle	[°]	1.8	1.8	1.8	1.8	1.8
Resistance/phase	[Ω]	2.30 ±10%	1.75 ±10%	0.5 ±10%	0.65 ±10%	0.33 ±10%
Inductivity/phase	[mH]	1.40 ±20%	3.30 ±20%	1.90 ±20%	3.20 ±20%	3.00 ±20%
Moment of inertia - rotor	[kgcm <sup>2</sup> ]	0.02	0.08	0.48	0.84	2.70
Shaft load, axial	[N]	7	7	15	15	65
Shaft load, radial	[N]	20	20	52	63	200

#### Encoder Operating voltage [VDC] 5 Signals/rotation [1/min] 500 Zero signal/index yes Line driver RS422 Protocol Signal shape [CW] А (Clockwise A/ motor rotation) В

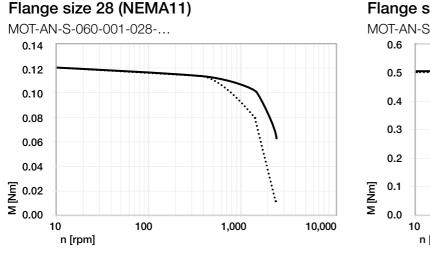
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### **Technical data**

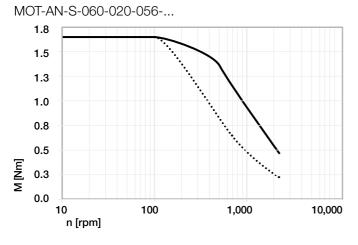
Plate size brake		28 NEMA11	42 NEMA17	56 NEMA23	60 NEMA23XL	86 NEMA34
Operating voltage	[VDC]	_	24 ±10%	24 ±10%	24 ±10%	24 ±10%
Output rating	[W]	_	8	10	10	11
Holding torque	[Nm]	_	0.4	1.0	1.0	2.0
Mass moment of inertia	[kgcm <sup>2</sup> ]	_	0.01	0.02	0.02	0.07
Mass moment		28	42	56	60	86
of inertia		NEMA11	NEMA17	NEMA23	NEMA23XL	NEMA34
Product weight	[kg]	0.25	0.32	1.12	1.56	3.20
With encoder	[kg]	0.27	0.34	1.14	1.58	3.30
With encoder and brake	[kg]	_	0.58	1.36	1.82	3.60
Operating data						
Ambient temperature	[°C]	–10 to +50				
Max. allowable temperature increase	e [°C]	80				
Insulation class		В				
Air humidity (non condensing)	[%]	85				
IP rating - motor housing		IP65 (shaft seal IP52, motor with stranded wires IP40)				
CE conformity		EMC directive				

# drylin® E | Stepper motors | Characteristic curves

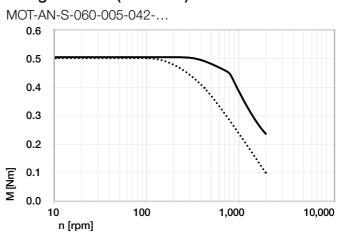
Characteristic curves



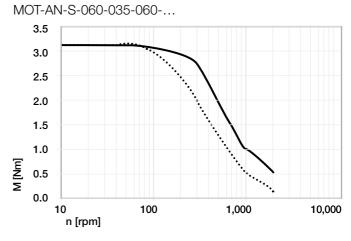
### Flange size 56 (NEMA23)



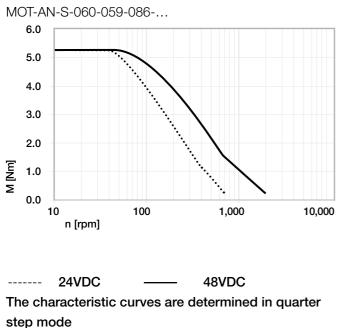
Flange size 42 (NEMA17)



### Flange size 60 (NEMA23XL)



### Flange size 86 (NEMA34)



## drylin® E | Stepper motors | Order key

Order key MOT-AN-S-060-020-056-M-A-AAAA	
MOT-AN-S-060-020-056-M-A-AAAA	Specification AAAA: Standard AAAC: Encoder AAAD: Encoder & brake Options A: Without C: Incremental encoder D: Incremental encoder & brake Motor connection M: Metric connector L: Stranded wires Distance over hubs 028: 28mm (NEMA11) 042: 42mm (NEMA17) 056: 56mm (NEMA23) 060: 60mm (NEMA23XL) 086: 86mm (NEMA34) Holding torque 001: 0.1Nm 005: 0.5Nm 020: 2.0Nm 035: 3.5Nm 035: 3.5Nm 035: 3.5Nm 059: 5.9Nm Maximum voltage 060: 60V/DC Motor type S: Stepper motor Type AN: Design Product type MOT: Motor

More information ► www.igus.eu/drylinE

